**Causal Representation Learning and Optimal Intervention Design** 

### Caroline Uhler (MIT & Broad Institute)



### Need for causal representation learning

### Huge amounts of unlabeled data of many different modalities



Representation learning allows integrating different modalities and extracting latent structures that capture intrinsic behavior without labeled data



Similar to Twitter Netflix movie corpus: 60pb Total data currently under management at Broad: ~100pb

### Need for causal representation learning

# Huge amounts of unlabeled data of many different modalities



Representation learning allows integrating different modalities and extracting latent structures that capture intrinsic behavior without labeled data

## Understanding the underlying mechanisms / causal relationships is critical in biomedical sciences





We need a theory of causal representation learning! Perturbations (CRISPR, drugs, ...) represent unique opportunity!

### Gene regulation and structural equation models

**Ex:** Gene regulatory network for pregastrular Sire **Sewell Wright** D\_d endomesoderm specification in sea urchins developed the foundation of 6,3G' LiCl-GSK-3 Maternal Inputs Mat G-cadherin causal inference Mat cß Mat Notch Mat SoxB1 Mat Otx nβ-TCF\_ECNS Nucl. Chance by studying "frizzled GSK-3 ECNS LICI Nucl. frizzled la lb Blimp1/Krox RhoA G" heredity unkn mes/end r nβ-TCF unkn vegetal activ nβ-TCF Ubig -Ubiq a Pmar1 R of mic SU(H) SoxB1 Wnt8 Su(H):NIC la lb Blimp1/Krox Hnf 6 α Otx Eve Ubiq Krl causal structural Ubiq r11 r7 Delta Notch Hnf 6 PMC unkn mes activ la 1b Blimp1/Krox 5 R of mic equation models Sewell Wright, 1920 Fox Dam Nrl Nrl Ubiq Endoderm Gcm unkn mes activ Hox11/13b [ Ubiq Ets1 GataC (oral) Alx1 r7 r11 Delta GataE Causal relations given by Krl Brn1/2/4 FoxB Dri Snail directed network; each Bra Alx1 Gcm (abo)  $X_1 \leftarrow f_1(X_3, \epsilon_1)$ FoxA Gsc FoxB VEGFR VEGF Eve Hox11/13b Mesoderm node is associated with Not Endomesoderm Veg1 Endo Skel  $X_2 \leftarrow f_2(X_1, \epsilon_2)$  $(X_3)$  $(X_2)$ a random variable; Endo Sm50 Msp130 Msp-L SuTx CAPK Dpt Pks **OrCT Kakapo** OrCT Kakapo  $X_3 \leftarrow f_3(\epsilon_3)$ stochasticity introduced Mes Sm30 G-cadherin Ficolin FvMo1,2,3 Decorin  $X_4 \leftarrow f_4(X_2, X_3, \epsilon_4)$ by independent noise Eric H. Davidson, 2006 variables  $\epsilon_i$ 

#### **Defining interventional distributions:**

- Intervention on  $X_2$ :  $do(X_2 = c)$
- $p(X_3 \mid do(X_4 = c)) = p(x_3) \neq p(x_3 \mid x_4)$ , but  $p(X_4 \mid do(X_3 = c)) = p(x_4 \mid x_3) \neq p(x_4)$

Intervention defines probabilistic operation that is different from conditioning and marginalization

Judea Pearl, 1995

### **Motivation: Cell state engineering**

- Engineering cell states: rejuvenation, regenerative & personalized medicine
- Achievable e.g. through: combinations of transcription factors (humans  $\sim$  2000)



Pluripotency

**iPSCs** 

ESC

Space of possible perturbations and relevant contexts is combinatorial & continuous!

### Causal structure discovery

Foundations for learning causal networks from observational data were developed at CMU by **Spirtes, Glymour & Scheines** in 1990s:

These algorithms assume faithfulness, i.e., that causal effects cannot cancel each other out



# Learning network on 100 nodes requires >>10^100 samples

Uhler et al., Ann. Statist., 2013; Raskutti & Uhler, Stat, 2018

UAI contributions: Malinsky, Rios, Moffa, Kuipers, Kiyavash, Choo, Shiragur, Claassen, Mooij, Koivisto, Evans, Cussens, Richardson, Cooper, Shimizu, Meek,...

- **Problem:** number of conditional independence tests
- Developed greedy sparest permutation algorithm that is consistent under strictly weaker conditions [Wang, Solus, Yang & U., '17]
- Building on Eberhardt's formalism, we extended this to first provably consistent algorithm for inferring causal network from observational & interventional data
- Computationally scales to graphs with 1000s of nodes, but not performance-wise



Yang, Katcoff & U., '18, Squires, Wang & U., '20,

Recent review: Squires & U., Causal structure learning: a combinatorial perspective, FoCM 2022

### **Causal transport and multi-modality**

#### How to predict the effect of unseen interventions/perturbations?



#### **Transport to new contexts**

#### **Transport to new perturbations**

How to think of causal variables in images? Can multi-modality help?

### Multi-modal autoencoders for learning causal features



Yang et al., ICML Workshop 2019 & Nature Communications, 2021

# Multi-modal integration for genetic association studies



Radhakrishnan et al., Nature Communications 2023

#### Multi-modal learning as a tool for causal feature discovery by learning integrated latent spaces:

Causal features should be invariant to modality in which they are measured

**Related work:** 

Invariant prediction for causal inference: Peters, Buehlmann, Meinshausen Invariant risk minimization: Arjovsky, Bottou, Gulrajani, Lopez-Paz

### Learning latent causal graph from multi-modal data



**Theorem:** The number of shared latent nodes and the joint domain distribution is identifiable. If there are no edges between the shared and domain-specific latent components and each shared latent node has at least 2 pure children, then also the shared latent graph is identifiable.

> *Sturma, Squires, Drton & Uhler, arXiv:2302.00993* (building heavily on Kun Zhang's recent work)

### Learning latent causal graph from interventional data

Given observational and perturbational data  $X, X^g$ :

- learn a generative model for  $\mathbb{P}(X^g|X,g)$ ,
- the grouping of targeted variables  $I = \{g\}$ ,
- and the causal graph between *I*.



**Theorem:** If interventional data from at least one intervention per latent node is available, then the latent interventional targets and the causal structure between the latent variables are identifiable (up to permutation), in theory as well as algorithmically using our discrepancy-VAE.

Zhang, Squires, Greenewald, Srivastava, Shanmugam & Uhler, arXiv:2307.06250



Related:Identifiability results under hard interventions in linear modelSquires, Seigal, Bhate & Uhler, ICML 2023Causal variable learning:Kun Zhang, Eberhardt, Sridhar, Hartford,...Disentanglement: Schoelkopf, Bengio,...

### Causal transport: blackbox or causal model?



Given the causal graph, then necessary and sufficient conditions for causal transportability (i.e. transport across contexts) are known [Bareinboim & Pearl, NeurIPS 2014, PNAS 2016, etc.]

# Black-box versus causal model: Transport problem to new genetic perturbations seems the hardest problem because of missing prior?

### Causal matrix completion using neural tangent kernel



CMap (Full Dataset)

Mean Over Cell Type FalRTC DNPP NTK Evaluation Metric\* (Naïve Baseline) (Llu et al. 2013) (Hodos et al. 2018) (Ours) 0.374 ± 0.0004 0.545 ± 0.0003 0.556 ± 0.0003 0.572 ± 0.0002 Pearson r 0.296 ± 0.0004 0.320 ± 0.0002 Mean R<sup>2</sup> 0.134 ± 10^(-5) 0.286 ± 0.0003 Mean Cosine 0.371 ± 10^(-5)  $0.536 \pm 0.0004$  $0.541 \pm 0.0004$  $0.554 \pm 0.0002$ Similarity

| Evaluation<br>Metric*     | Mean Over Cell Type<br>(Naïve Baseline) | FaLRTC<br>(Liu et al. 2013) | DNPP<br>(Hodos et al. 2018) | NTK<br>(Ours) |
|---------------------------|---|-----------------------------|-----------------------------|---------------|
| Pearson r                 | 0.450                                   | 0.544                       | 0.538                       | 0.573         |
| Mean R <sup>2</sup>       | 0.197                                   | 0.285                       | 0.278                       | 0.324         |
| Mean Cosine<br>Similarity | 0.448                                   | 0.536                       | 0.532                       | 0.565         |

(Sparse Regime)

\*Higher is better, with a maximum of 1.

#### Radhakrishnan et al., PNAS 2022

#### Related work: Synthetic controls / interventions: Shah, Agarwal, Abadie

### Where we are headed: from prediction to control

# If we are able to predict the effect of an unseen intervention, we should be able to optimize interventions to induce a particular cell state transition



Algorithm iteratively updates causal model belief using samples acquired so far from different interventions, and selects next intervention that is most informative and will move the distribution to the desired state using causally informed acquisition function:



Our acquisition function is theoretically sound (information-theoretic bounds, provably recovers optimal intervention) and computationally efficient (closed-form evaluation and fast gradient-based optimization for linear Gaussian SEM and the problem of mean matching)

Zhang, Squires et al., to appear in Nature Machine Intelligence 2023

Related work: Active learning/Bayesian opt/Bandits: Gulchin, Aglietti, Bareinboim; also: Zhang, Squires & U., NeurIPS 2021

Active learning of interventions:

Biomedical sciences are uniquely suited not only to being one of the greatest beneficiaries of research in causality/ML but also one of the greatest sources of inspiration for it.

- While in biology we have access to large-scale multi-modal and interventional datasets, the underlying causal model incl. causal variables is generally unknown
- Optimally making use of large-scale multi-modal and interventional datasets requires a theoretical and algorithmic framework for causal representation learning
- Many open problems regarding how to optimally combine approaches from representation learning with causality
- Concentrated on Pearl's level 2 (predicting the effect of unseen interventions): instead of combining methods from level 1 and level 3, do we need a completely new theoretical and algorithmic framework?

#### Pearl's causal hierarchy



J. Pearl, The Book of Why, 2018

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